

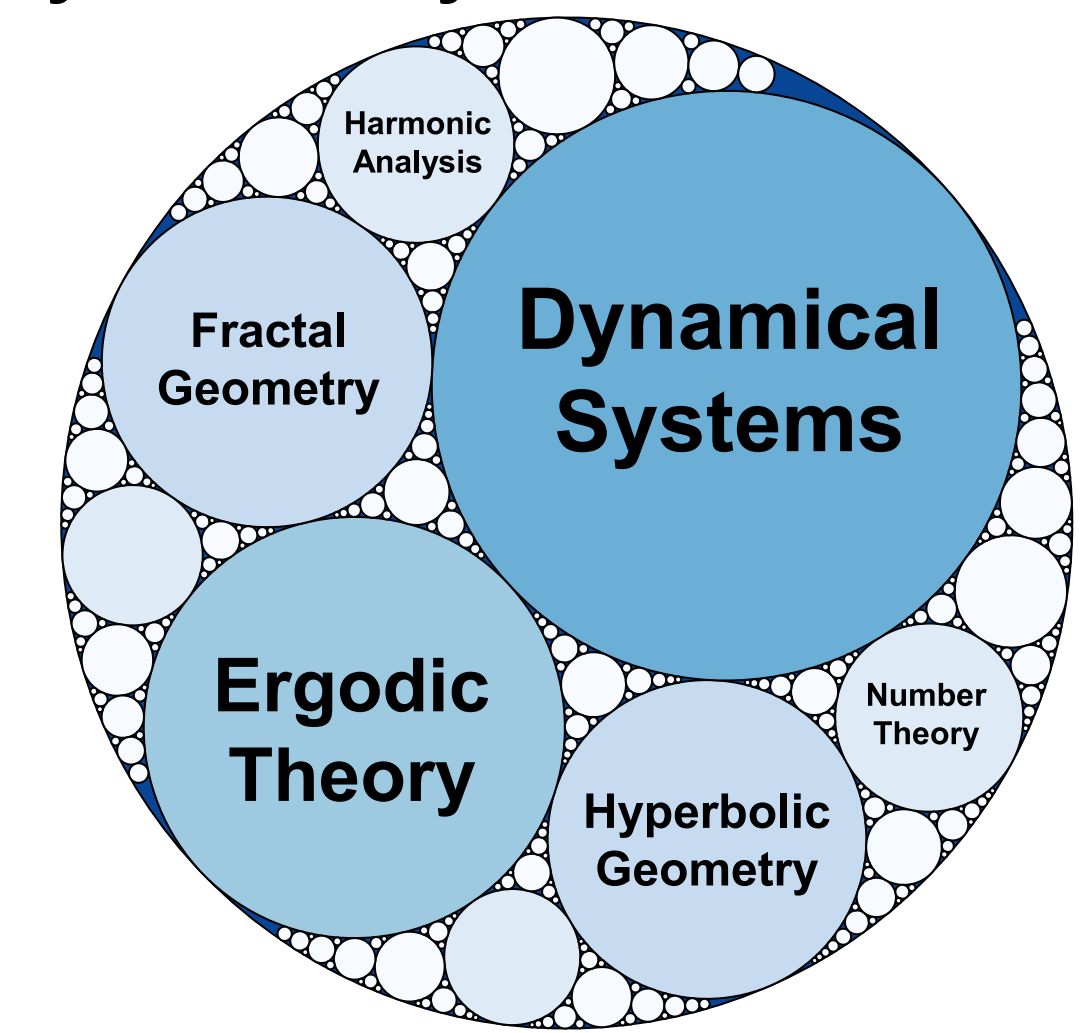
Augmented trees for infinite IFSs

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Abstract

We generalize the notion of augmented tree [LW17] to infinite IFS of similarity mappings on \mathbb{R}^d . This graph Γ is δ -hyperbolic in the sense of Gromov and allows us to define the hyperbolic boundary. The space $\partial^{\#}\Gamma$ of equivalence classes of geodesic rays is a subset of the hyperbolic boundary. The usual coding map adapted to the notion of augmented tree defines a Hölder equivalence of between $\partial^{\#}\Gamma$ and the limit set of the IFS.

Notation

Let $X \subset \mathbb{R}^d$ be a compact set and wlog $|X| = 1$. For an infinite index set $I \subset \mathbb{N}$, consider an IFS Φ of contractive similarity mappings $\varphi_i: X \rightarrow X$, $i \in I$. Denote by R_i the contraction ratio of φ_i , $i \in I$, and assume wlog $\lim_{i \in I} R_i = 0$ and wlog $R_i \leq R_j$ for $i \leq j$.

- I^n : words of n letters from alphabet I , $n \in \mathbb{N}$; $I^0 := \{()\}$, where $()$ is the empty word
- $I^* := \bigcup \{I^n | n \in \mathbb{N}_0\}$
- $I^{\mathbb{N}}$: sequences of letters from alphabet I ; for $\xi \in I^{\mathbb{N}}$, $\xi|_n$: the prefix of ξ of n letters, $n \in \mathbb{N}$

For $\omega = (\omega_1, \dots, \omega_n) \in I^n$, $n \in \mathbb{N}_0$, let

- if $n = 0$: $\varphi_{()} := \text{Id}_{\mathbb{R}^d}$, else: $\varphi_{\omega} := \varphi_{\omega_1} \circ \dots \circ \varphi_{\omega_n}$ with ratio R_{ω}
- for $\tau = \tau_1 \dots \tau_m \in I^m$, $m \in \mathbb{N}_0$: $\omega\tau := \omega_1 \dots \omega_n \tau_1 \dots \tau_m \in I^{n+m}$
- $\omega^- := (\omega_1, \dots, \omega_{n-1})$

The limit set of the IFS is $J = \bigcup_{\xi \in I^{\mathbb{N}}} \bigcap_{n=1}^{\infty} \varphi_{\xi|_n}(X)$. It is not closed in general.

Following the ideas in [LW17] we construct a graph, an *augmented tree*, associated to the IFS Φ .

Augmented tree (Γ^*, \mathcal{E})

Let $R = R_1$ and consider the subsets $F_k \subset I^*$ for $k \in \mathbb{N} \cup \{0\} = \mathbb{N}_0$ given by

$$F_0 := \{()\}, \quad F_k := \{\omega \in I^* \mid R_{\omega} \leq R^k < R_{\omega^-}\}, \quad k \in \mathbb{N}. \quad \Rightarrow \quad \bigcup \{F_k \mid k \in \mathbb{N}_0\} = I^*$$

Note that contrary to the construction in [LW17], the sets F_k , $k \in \mathbb{N}_0$, are not disjoint. For each $k \in \mathbb{N}_0$, we interpret the sets F_k as level sets of vertices Γ_k via function

$$w: \Gamma_k \rightarrow F_k, \quad w(x) = \omega \quad \text{if } x \text{ corresponds to the word } \omega$$

and extend it to $w: \Gamma^* := \bigcup \Gamma_k \rightarrow I^*$, on vertex set Γ^* .

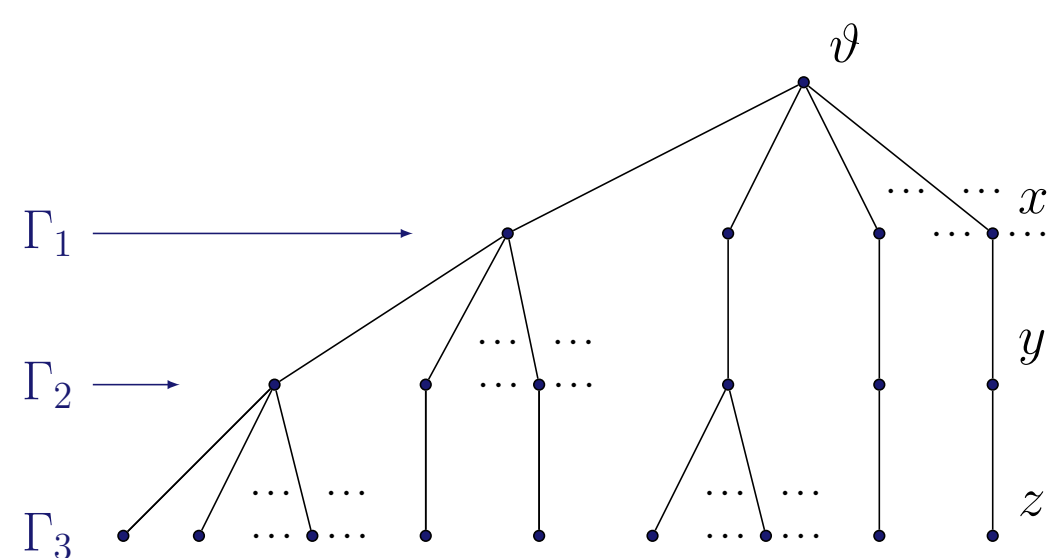


Figure 1: Example of vertical structure of the graph Γ . For the vertices x, y and z we have $w(x) = w(y) = w(z)$.

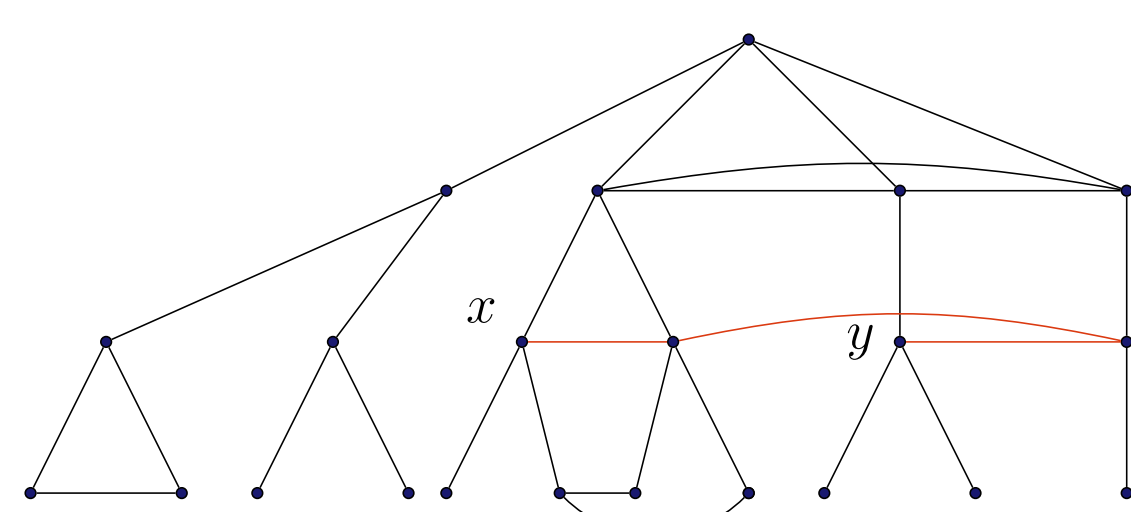


Figure 2: Example of finite subgraph of Γ with vertical and horizontal edges. The path from x to y is a horizontal geodesic.

Definition of augmented tree Γ

The vertex set is Γ^* . Let ϑ with $w(\vartheta) = ()$, be the root. Fix $\kappa > 0$.

- vertical (unoriented) edges \mathcal{E}_v

$$(x, y) \in \mathcal{E}_v \Leftrightarrow x \in \Gamma_k \wedge y \in \Gamma_{k+1} \text{ for some } k \in \mathbb{N}_0 \wedge w(y) = w(x)\zeta \text{ for some } \zeta \in I^*$$

- horizontal (unoriented) edges \mathcal{E}_h :

$$(x, y) \in \mathcal{E}_h \Leftrightarrow x, y \in \Gamma^k \text{ for some } k \in \mathbb{N}, x \neq y \wedge \text{dist}(\varphi_{w(x)}(X), \varphi_{w(y)}(X)) \leq \kappa R^k.$$

- augmented tree: $\Gamma = (\Gamma^*, \mathcal{E})$ with set of edges: $\mathcal{E} = \mathcal{E}_v \cup \mathcal{E}_h$

- (integer valued) graph metric on Γ^* : d

path $[x_1, x_2, \dots, x_l] \subset (\Gamma^*, \mathcal{E})$ of length l is a geodesic $\Leftrightarrow d(x_1, x_l) = l$

infinite path $[x_1, x_2, \dots]$ is geodesic ray $\Leftrightarrow d(x_k, x_l) = |l - k|$ for all $k, l \in \mathbb{N}$

$\Pi :=$ set of all geodesic rays starting at ϑ

- for $k, l \in \mathbb{N}_0$ and $y \in \Gamma_{k+l}$: $y^{-1} = x$ if $x \in \Gamma_k$ and \exists path $c \in \mathcal{E}_v$ connecting x and y

Properties of augmented tree Γ

The graph $(\Gamma^*, \mathcal{E}_v)$ is a tree with root ϑ and with vertices of infinite degree.

In particular, we have $I \equiv \Gamma_1$ and $\deg \vartheta = \infty$.

- $\forall k \in \mathbb{N} \forall x \in \Gamma_k \forall 0 \leq l \leq k: \varphi_{w(x)}(X) \subset \varphi_{w(x^{-1})}(X)$

- If $x, y \in \Gamma_k$ for some $k > 0$ and $(x, y) \in \mathcal{E}$ then either $x^{-1} = y^{-1}$ or $(x^{-1}, y^{-1}) \in \mathcal{E}_h$.

- $\forall \xi \in I^{\mathbb{N}} \forall k \in \mathbb{N}: \exists n(k) \in \mathbb{N} \exists x \in \Gamma_k: \xi|_{n(k)} = w(x)$

- $\forall \xi \in I^{\mathbb{N}}: \bigcap_{n=1}^{\infty} \varphi_{\xi|_n}(X) = \bigcap_{k=1}^{\infty} \varphi_{w(x_k)}(X)$ where x_k such that $w(x_k) = \xi|_{n(k)}$, $n(k)$ as above

Proposition

There exists $\gamma < \infty$ such that every horizontal geodesic in (Γ, d) is bounded in length by γ .

Hence, if $\pi = [\vartheta, x_2, x_3, \dots]$ is geodesic ray then $\pi \subset (\Gamma^*, \mathcal{E}_v)$. Furthermore, for $\xi \in I^{\mathbb{N}}$ and $(x_k)_k \in \Gamma^1 \times \Gamma^2 \times \dots$ with $w(x_k) = \xi|_{n(k)}$, the path $[\vartheta, x_1, x_2, \dots]$ is a geodesic ray.

δ -hyperbolicity

Following [Woe00], we recall the notions of δ -hyperbolic spaces and δ -Gromov hyperbolic graphs.

δ -hyperbolic space

Let (Γ, ρ) be a geodesic space. For $x, y \in \Gamma$ write $\pi[x, y]$ for a geodesic path from x to y , which in general is not unique. The space (X, d) is δ -hyperbolic for $\delta \geq 0$ if the following holds. For any $x, y, z \in \Gamma$ consider triangle composed by geodesic paths $\pi[x, y]$, $\pi[y, z]$, $\pi[z, x]$. Then any point on one of the three sides is at distance of at most δ from some point on one of the other sides.

Gromov product & δ -Gromov hyperbolic graphs

Let (Γ, d) be a graph with graph metric d and ϑ a vertex in Γ . For vertices x, y in Γ define Gromov product of x and y wrt reference point ϑ as

$$|x \wedge y| := \frac{1}{2}(d(x, \vartheta) + d(y, \vartheta) - d(x, y)).$$

The graph (Γ, d) with graph metric d is δ -Gromov hyperbolic if for some choice (and hence any choice with some other δ) of reference point there exists $\delta \geq 0$

$$|x \wedge y| \geq \min\{|x \wedge z|, |y \wedge z|\} - \delta, \quad x, y, z \in \Gamma.$$

Consider a graph (Γ, d) and extend the graph metric d in canonical way to edges. Then

$$(\Gamma, d) \text{ is } \delta\text{-Gromov hyperbolic} \Rightarrow (\Gamma, d) \text{ is } 4\delta\text{-hyperbolic}$$

$$(\Gamma, d) \text{ is } \delta\text{-hyperbolic space} \Rightarrow (\Gamma, d) \text{ is } 3\delta\text{-Gromov hyperbolic}$$

The graph (Γ^*, \mathcal{E}) is δ -hyperbolic

We now return to the graph $\Gamma = (\Gamma^*, \mathcal{E})$ from above.

Proposition

Let (Γ, d) be the augmented tree for fixed $\kappa > 0$ with the usual graph metric d .

- Γ is δ -hyperbolic \Leftrightarrow every horizontal geodesic is bounded in length.
- Hence, (Γ, d) is δ -hyperbolic space for some $\delta \geq 0$.

Hyperbolic ultrametric ρ_a & hyperbolic boundary of Γ

For $\delta \geq 0$ such that Γ is δ -hyperbolic, let $a > 0$ such that $\exp(3\delta a) < \sqrt{2}$.

- Define ultrametric ρ_a wrt reference point $\vartheta = ()$ of $x, y \in \Gamma^*$:

$$\rho_a(x, y) := \begin{cases} \exp(-a|x \wedge y|), & x, y \in \Gamma^*, x \neq y \\ 0, & x = y. \end{cases}$$

- There exists a metric θ_a equivalent to ρ_a .

- Consider the completion $\bar{\Gamma}$ of (Γ, θ_a) . The hyperbolic boundary is $\partial\bar{\Gamma} := \bar{\Gamma} \setminus \Gamma$.

Proposition

- Let $(x_n)_n$ be a sequence in Γ^* with $d(x_n, \vartheta) \rightarrow \infty$.

- $(x_n)_n$: Cauchy sequence wrt $\theta_a \Leftrightarrow (x_n)_n$: Cauchy sequence wrt $\rho_a \Leftrightarrow \lim_{m, n \rightarrow \infty} |x_n \wedge x_m| = \infty$

- Cauchy sequences $(x_n)_n$ and $(y_n)_n$ in (Γ^*, θ_a) define the same boundary point $\Leftrightarrow \lim_{n \rightarrow \infty} |x_n \wedge y_n| = \infty$.

Geodesic rays

Geodesic rays $\pi = [x_1, x_2, \dots]$, $\pi' = [y_1, y_2, \dots]$ in Γ are equivalent iff they stay at finite distance from each other, i. e. $\liminf_{n \rightarrow \infty} d(y_n, \pi) < \infty$. This relation is an equivalence relation on geodesic rays.

- If a geodesic ray $\pi = [x_1, x_2, \dots]$ starts in a vertex $x_1 \neq \vartheta$ there exists a geodesic path $[\vartheta = z_1, \dots, z_l]$ with $l \in \mathbb{N}$, and $k \in \mathbb{N}_0$, such that $\tilde{\pi} := [\vartheta, z_2, \dots, z_l, x_k, \dots]$ is a geodesic ray starting in ϑ .

- A geodesic ray $\tilde{\pi}$ constructed as above is equivalent to π .

- If $\pi = [x_1 = \vartheta, x_2, \dots]$ is a geodesic ray then $(x_n)_n$ is a Cauchy sequence.

Geodesic boundary $\partial^{\#}\Gamma$

Let us define the geodesic boundary $\partial^{\#}\Gamma$ as the quotient Π / \sim .

- In general, $\partial^{\#}\Gamma \subseteq \partial\bar{\Gamma}$.

- The Gromov product and the ultrametric ρ_a can be extended to $\partial^{\#}\Gamma$ via

$$|[\pi] \wedge [\pi']| := \inf\{\liminf_{n \rightarrow \infty} d(y_n, \pi) \mid \pi \in [\pi], \pi' = [\vartheta, y_1, y_2, \dots] \in [\pi']\}.$$

- Define coding map $c: \partial^{\#}\Gamma \rightarrow J$ by

$$c([\pi]) := \bigcap_{k=1}^{\infty} \varphi_{w(x_k)}(X), \quad \text{where } [\vartheta, x_1, x_2, \dots] \in [\pi].$$

Theorem

The coding map c is a well-defined bijection $\partial^{\#}\Gamma \rightarrow J$.

The geodesic boundary $\partial^{\#}\Gamma$ is Hölder equivalent to limit set J : $\exists C > 0$ such that, with $\alpha := -1/a \ln R$,

$$C^{-1}|c([\pi]) - c([\pi'])| \leq \rho_a([\pi], [\pi'])^\alpha \leq C|c([\pi]) - c([\pi'])|, \quad [\pi], [\pi'] \in \partial^{\#}\Gamma.$$

Work in progress

For infinite index set $I \subset \mathbb{N}$, let φ_i be a conformal IFS (cIFS) Ψ on compact set $X \in \mathbb{R}^d$. That is, each φ_i is a C^1 -conformal injective contraction and there exists open bounded connected set $V \supset X$ such that φ_i can be extended to C^1 -conformal injective contraction on V , $i \in I$ (cf. [MU96]). For $\omega \in I^*$ denote $R_{\omega} := \sup_{v \in V} \|D\varphi_{\omega}(x)\|_{\text{op}}$. Let Ψ have the bounded distortion property and satisfy $\lim_{i \in I} R_i = 0$. We can adapt the construction of an augmented tree for conformal case in an obvious way. Denote the limit set of Ψ by J .

Proposition

For fixed $\kappa > 0$, let $\Gamma = (\Gamma^*, \mathcal{E})$ be augmented tree for cIFS Ψ . Then the previous results are valid for Γ and limit set J .

- Γ is δ -hyperbolic graph and every horizontal geodesic is bounded in length by a constant γ .

- The geodesic boundary $\partial^{\#}\Gamma$ is Hölder equivalent to the limit set J .

(Proof in progress.)

Open questions

- For IFS/ cIFS/ GDMS, does the open set condition guarantee the identity $\partial\bar{\Gamma} = \partial^{\#}\Gamma$?
- How does the concept of an augmented tree, in particular its hyperbolic and geodesic boundaries, relate to the concepts of limit set and (uniform) radial limit set of Kleinian groups?
- How do these concepts relate regarding the phenomenon of “dimension drop”?

References

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